First and Second Order Transient Circuits

When conditions in a circuit change, for example when you turn it on or switch operating states, its behavior is <u>transient</u>. Circuit parameters change over some time allowing the change of state, then approach <u>steady state</u> operation.

Note periodic signals are changing over time, but since conditions repeat at regular intervals, the circuit reaches a periodic (AC) steady state.

At this stage, to analyze transients we will work in the time domain -> with equations including t or derivatives d/dt.

Consider a camera flash operating from a battery:



The battery charges a capacitor (fairly slowly). When the switch is moved (depressed) the capacitor discharges rapidly through the lamp.

We may be interested in the charging and discharging process:



Consider the discharge circuit:



When the switch is closed, KCL at a node between R and C:

$$C\frac{dv_c(t)}{dt} + \frac{v_c(t)}{R_L} = 0$$
$$\frac{dv_c(t)}{dt} + \frac{1}{CR_L}v_c(t) = 0$$

Which has a solution

$$v_c(t) = v_o e^{\frac{-t}{R_L C}}$$

Exponential charging with a rate that depends on the RC product.

First Order Transients

In general, the problem will have the form:

$$\frac{dx(t)}{dt} + ax(t) = f(t)$$

And the solution can be a linear combination of forced response (including f(t)) and natural response (with f(t) = 0) so:

 $x(t) = x_p(t) + x_c(t)$ (particular and complementary)

If we limit our cases to a constant for the forcing function (A), then a solution can also be a constant K₁:

$$\frac{dx_p(t)}{dt} + ax_p(t) = A$$
$$x_p(t) = K_1$$

For the homogeneous equation (=0)

$$\frac{dx_c(t)}{dt} + ax_c(t) = 0$$
$$\frac{1}{x_c(t)}\frac{dx_c(t)}{dt} = -a$$

You may recognize a solution

$$\ln(x_c(t)) = -at + c$$

Or

$$x_c(t) = K_2 e^{-at}$$

And we can put together a general solution:

$$x(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$$

Where K_1 is the steady state solution and τ is the time constant.

And we can solve problems by fitting our initial and final conditions or by writing and solving D.E.s.

Transient Circuit Analysis

-differential equation approach

-> write equation for voltage on a capacitor or current through an inductor.

Note: These quantities don't change instantaneously.



Write KCL:

$$C\frac{dv(t)}{dt} + \frac{v(t) - V_S}{R} = 0$$

Or

$$\frac{dv(t)}{dt} + \frac{v(t)}{RC} = \frac{V_S}{RC}$$

Which should have a solution

$$v(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$$

Substitute this into the differential equation:

$$\left(\frac{-K_2}{\tau}e^{\frac{-t}{\tau}}\right) + \frac{1}{RC}\left(K_1 + K_2e^{\frac{-t}{\tau}}\right) = \frac{V_S}{RC}$$

Noting that the constant terms must be equal:

$$\frac{K_1}{RC} = \frac{V_S}{RC}$$

Or
$$K_1 = V_S$$

The exponential terms must also be equal so:

$$\frac{K_2}{\tau} = \frac{K_2}{RC}$$

Or $\tau = RC$

We still need K_2 -> consider the initial condition

$$V(0) = 0V = K_1 + K_2 = V_s + K_2$$

$$K_2 = -V_s$$

And

$$v(t) = V_S - V_S e^{\frac{-t}{RC}} = V_S \left(1 - e^{\frac{-t}{RC}} \right)$$

If we had an inductor instead



Write KVL:

$$L\frac{di(t)}{dt} + Ri(t) = V_S$$

And

$$i(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$$
$$\left(\frac{-K_2}{\tau} e^{\frac{-t}{\tau}}\right) + \frac{R}{L} \left(K_1 + K_2 e^{\frac{-t}{\tau}}\right) = \frac{V_S}{L}$$

Constant terms:

$$\frac{K_1R}{L} = \frac{V_S}{L}$$
$$K_1 = \frac{V_S}{R}$$

Exponential terms:

$$\frac{K_2}{\tau} = \frac{K_2 R}{L}$$

$$\tau = \frac{L}{R}$$

And at t =0

$$i(0) = 0 = \frac{V_S}{R} + K_2$$
$$K_2 = -\frac{V_S}{R}$$

So

$$i(t) = \frac{V_S}{R} \left(1 + e^{-\frac{R}{L}t} \right)$$

And if we want $v_R(t)$:

$$v_R(t) = R \cdot i(t) = V_S \left(1 + e^{-\frac{R}{L}t} \right)$$

(similar to capacitor voltage in RC).

Transient Circuit Analysis Step by Step Approach

We still expect a solution

$$x(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$$

(x might be current or voltage)

Note as t -> ∞ $e^{\frac{-t}{\tau}} \rightarrow 0$ x(t) -> K₁

So if we find x(t) in steady-state (t -> ∞) with capacitor open circuit (for DC) and inductors short circuit (for DC), then x(t) = K₁.

Note at $t = 0 x(t) = K_1 + K_2$

Or at some time t_o:

$$x(t_o) = K_1 + K_2 e^{\frac{-t_o}{\tau}}$$

So if we know the initial value x(0) or the value at some time $x(t_o)$ we can also find K_2 .

Often the 'initial condition' is just after a switch moves and is determined by the circuit before the switch changed.

The time constant can be found from the Thevenin equivalent resistance at the terminals of C or L.

$$au = R_{th}C$$
 or $au = rac{L}{R_{th}}$

Example Find i(t) t > 0:



- 1) We expect: $v_c(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$
- 2) Initial capacitor voltage t = 0⁻ (steady state open circuit)
 - i(0⁻)= (36V-12V)/(2k+6k+4k) = 2mA
 - v_c(0⁻) = 36V 2mA X 2k = 32V
 - note i will change as soon as switch moves. v_c must be continuous.
- 3) At $t=0^+$ the switch connects 6k to ground. So new circuit is:



- 4) as t -> ∞ the capacitor is again open circuit
 - i(∞) = 36V/(6k+2k) = 4.5mA
 - v_c(∞)= 4.5mA X 6k = 27V = K₁
- 5) From the initial condition we know that:

•
$$v_c(0) = K_1 + K_2 e^0 = 32V \rightarrow K_2 = 32V - 27V = 5V$$

6) To find au we need the equivalent resistance seen by the capacitor



- Note the 4k resistor is still shorted out by the switch.
- Therefore $R_{th} = 6k//2k = 1.5k$
- So $\tau = R_{th} \cdot C = 1.5k \cdot 100\mu F = 0.15s$
- And our solution $v_c(t) = \left(27 + 5e^{\frac{-t}{0.15}}\right)V$
- The current is then easily found by ohm's law as: $i(t) = \frac{v_c(t)}{6k} = 4.5 + 0.83e^{\frac{-t}{0.15}}mA$



• Note the switch doesn't always change at t = 0 -> we may have an $e^{\frac{-t_0}{\tau}}$ term.

• e.g.
$$x(t) = x(\infty) + [x(t_o) - x(\infty)]e^{\frac{-(t-t_o)}{\tau}}$$

• be very careful applying formula solutions!

Pulse Response

Many circuits are characterized by their response to a unit impulse or unit step function. We'll just consider a step for now

Unit step function $u(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$

And a more general form: $u(t) = \begin{cases} 0 & t < t_o \\ 1 & t > t_o \end{cases}$

Note steps can be used to construct other functions, such as pulses:

$$v(t) = A[u(t) - u(t - T)]$$

is a pulse from 0 to T

$$v(t) = A[u(t - t_o) - u(t - (t_o + T))]$$

is a pulse from t_o to t_o+T

Note we also write such functions piece wise.



 $v_o(t) = 0$ for t < 0 (no source)

at t=0⁺ i_o = 0 (inductor) so v_o = 0V

as $t \rightarrow \infty$ if pulse did not end, inductor = short, v_o = 1/3 X 12V = 4V



 $R_{th} = 3\Omega \frac{****Note this is not obvious to a lot of students, but the 20hm resistor on the right is in series with the other two in parallel. Remember a circuit is a circle!$

so
$$\tau = \frac{L}{R} = \frac{2}{3} = 0.67s$$

 $v_o(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$
 $t \to \infty \quad K_1 = 4V$
 $t \to 0 \quad v_o(t) = 0 = K_1 + K_2 \to K_2 = -K_1 = -4V$

So

$$v_o(t) = 4\left(1 - e^{-\frac{3}{2}t}\right) \quad 0 < t < 1s$$

at $t = 1s \quad v_o(1) = 4\left(1 - e^{-\frac{3}{2}}\right) = 3.11V$

Now the pulse is turned off so eventually the voltage returns to zero. Therefore:

$$v_o(\infty) = 0 = K_1$$

The initial condition again gives us K_2 directly since K_1 is zero as 3.11V.

so
$$v_o(t) = 3.11e^{-\frac{3}{2}(t-1)}$$
 for $t > 1s$

You may want to read RLC - we will come back to this later!

Design Example

One application of capacitors is to smooth-out sudden voltage changes, since voltage in a capacitor cannot change instantaneously.

Capacitors are widely used for decoupling power supplies -> that is protecting circuits from rapid voltage fluctuations or disturbances.

Say we have a DC voltage source:



We would like a simple circuit to isolate a load from supply fluctuations.

We can do this with a single capacitor across the load:



Say our supply changes from $V_s \rightarrow V_s + \Delta V_s$ at time t = 0, and returns to V_s at t = t'



How will C_D influence the fluctuation in output voltage Δv_o ?

Voltage on C_D: $v_o(t) = K_1 + K_2 e^{\frac{-t}{\tau}}$

at
$$t = 0$$
 $v_o(0) = K_1 + K_2 = V_S - I_L R_S$

at $t = \infty$ $v_o(\infty) = K_1 = V_S + \Delta V_S - I_L R_S$ (for a step) used to get constants during a pulse And the time constant is just R_SC_D. so:

$$v_o(t) = (V_S + \Delta V_S - I_L R_S) - \Delta V_S e^{\frac{-t}{R_S C_D}}$$

This applies until t', when the voltage supply returns to Vs.

$$v_o(t') = (V_S + \Delta V_S - I_L R_S) - \Delta V_S e^{\frac{-t'}{R_S C_D}}$$
$$= V_S - I_L R_S + \Delta V_o$$

Or

$$\Delta V_S - \Delta V_o = \Delta V_S e^{\frac{-t'}{R_S C_D}}$$
$$\frac{\Delta V_S}{\Delta V_S - \Delta V_o} = e^{\frac{t'}{R_S C_D}}$$
$$R_S C_D = \frac{t'}{\ln\left(\frac{\Delta V_S}{\Delta V_S - \Delta V_o}\right)}$$

Or

$$C_D = \frac{\frac{t'}{R_S}}{\ln\left(\frac{\Delta V_S}{\Delta V_S - \Delta V_o}\right)}$$

Note the choice of C_D depends on voltage change, not magnitude.

Given the expected size and length of voltage disturbances, source R and desired fluctuation in load voltage, we can choose C_D .

However good decoupling ($\frac{\Delta V_o}{\Delta V_S}\ small)$ requires large C_D value.